

Multiresolution Analysis

Recall: Any finite energy signal f can be decomposed in an orthogonal wavelet basis $\{\psi_{j,k}\}_{j,k \in \mathbb{Z}^2}$

$$f = \sum_{j=-\infty}^{\infty} \sum_{k=-\infty}^{\infty} \langle f, \psi_{j,k} \rangle \psi_{j,k}$$

Burrus notation:

$$\{\psi_{j,k}(t) = 2^{j/2} \psi(2^j t - k)\}_{j,k \in \mathbb{Z}^2}$$

The partial sum (at resolution 2^j)
(scale = $\frac{1}{\text{resolution}} = 2^{-j}$)

$$\sum_{k=-\infty}^{\infty} \langle f, \psi_{j,k} \rangle \psi_{j,k} = d_j$$

can be interpreted as the difference between two approximations of f at scales 2^{-j+1} and 2^{-j} .

d_j is simply the projection of f onto the subspace

$$W_j = \overline{\text{Span}_k \{ \psi_{j,k} \}}$$

← overbar denotes closure

d_j = "details of f at scale 2^j "

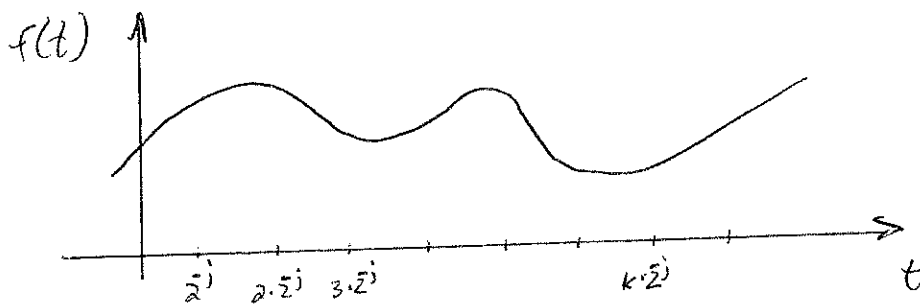
finer (smaller) scale \iff higher (larger) resolution
 $2^j \iff 2^{-j}$

Why multiresolution?

Adapting the resolution of our signal analysis allows us to process only the relevant details for a specific task.

ex. Burt & Adelson introduced the multiresolution image pyramid that can be used to code or process differently at different resolutions. This is crucial in modern image and video compression. Multiresolution image analysis also facilitates more advanced tasks such as image restoration, segmentation and object recognition.

Multiresolution Approximations



Analysis at scale 2^j

Compute local averages of f at positions $\{k \cdot 2^j\}_{k \in \mathbb{Z}}$ over intervals of width $\propto 2^j$

(scale 2^j)

Multiresolution analysis

Analysis of f over embedded grids of approximation.

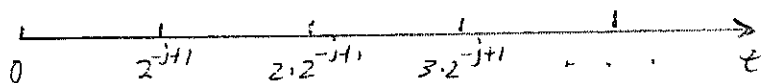
scale 2^j

resolution = 2^j

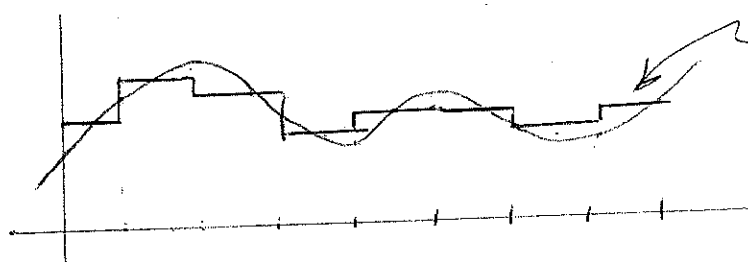


scale 2^{j+1}

resolution = 2^{j+1}

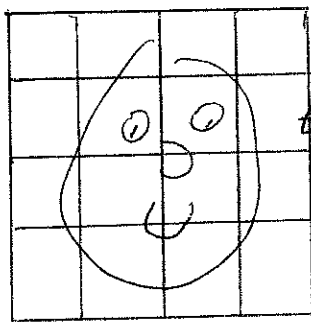


Recall, Haar wavelet analysis



levels of piecewise constant approximation are the local averages of f

Multiresolution Image Analysis



compute local average
over a neighborhood
of area proportional
to $(2^{-j})^2$

Multiresolution analysis of d-dimensional object

Compute local average over
neighborhood of measure $\approx 2^{-jd}$

Formally :

An approximation of a function
 $f \in L^2(\mathbb{R})$ at scale 2^j is defined
as an orthogonal projection of f
onto a subspace $V_j \subset L^2(\mathbb{R})$
(low resolution)

Definition : Multiresolution Analysis (MRA)

A sequence $\{V_j\}_{j \in \mathbb{Z}}$ of closed subspaces of $L^2(\mathbb{R})$ is a multiresolution analysis (or decomposition) of $L^2(\mathbb{R})$ if the following properties hold:

$$\textcircled{1} \quad f \in V_j \iff f(t - 2^{-j}k) \in V_j \quad \forall j, k$$

$$\textcircled{2} \quad V_{j+1} \supset V_j \quad \forall j$$

$$\textcircled{3} \quad f(t) \in V_j \iff f(2t) \in V_{j+1} \quad \forall j$$

$$\textcircled{4} \quad V_{-\infty} = \lim_{j \rightarrow -\infty} V_j = \{0\} \quad \leftarrow \text{contains only the "zero" function}$$

$$\textcircled{5} \quad V_{\infty} = \lim_{j \rightarrow \infty} V_j = L^2(\mathbb{R})$$

$\textcircled{6}$ There exists a function $\phi(t)$

such that

$$\{\phi(t-k)\}_{k \in \mathbb{Z}}$$

is a Riesz basis of V_0 .

scale 2^j

Note: Here j refers to resolution 2^j , so

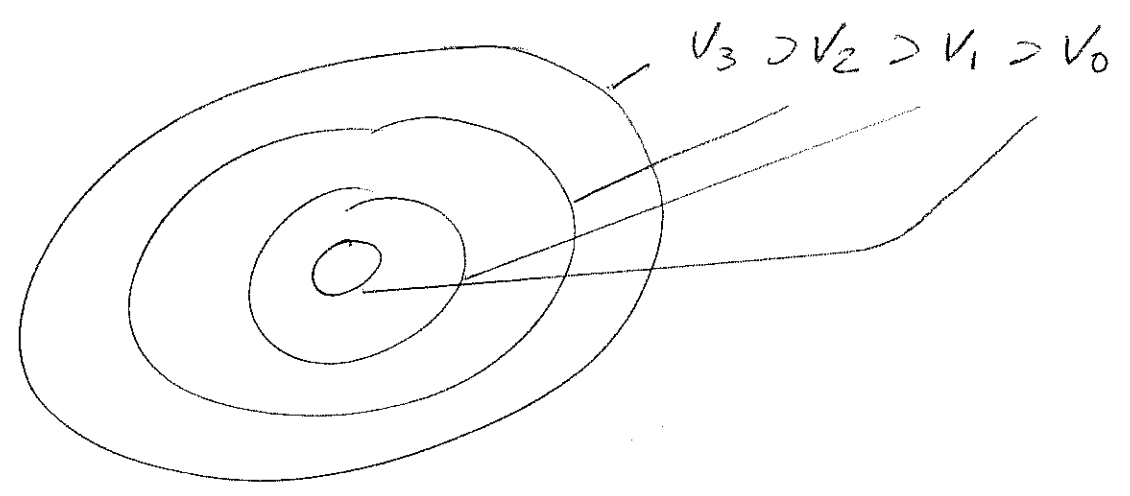
V_{j+1} is a finer scale

(higher resolution $2^{(j+1)}$) subspace
than V_j (resolution 2^j)

This is the convention of Burrus et al.

Others index the subspaces in
the inverse manner. That is,
they let j denote scale 2^j rather
than resolution so that $V_{j+1} \subset V_j$
(e.g., Mallat's book)

Multiresolution Subspaces



"Nested subspaces"

The fact that the multiresolution subspaces are nested guarantees that an approximation at resolution 2^j (in V_j) contains all the necessary information to compute an approximation at a lower resolution 2^{j-1} (in V_{j-1}).

Let P_{V_j} denote the projection operator projecting $f \in L^2$ to $f_j \in V_j$

$$V_{-\infty} = \{0\} \implies \lim_{j \rightarrow -\infty} \|P_{V_j} f\| = 0 \quad \forall f \in L^2(\mathbb{R})$$

implying that as the resolution $2^j \rightarrow 0$ we lose all the details of f

$$V_{\infty} = L^2(\mathbb{R}) \implies \lim_{j \rightarrow \infty} \|P_{V_j} f - f\| = 0$$

showing that the signal approx

$f_j = P_{V_j} f$ converges to the true signal as resolution $2^j \rightarrow \infty$.

(rate at which $\|P_{V_j} f - f\| \rightarrow 0$ depends on regularity of f) 24

Riesz Bases

Less restrictive than insisting on an orthogonal basis.

$\{e_n\}_{n \in \mathbb{Z}}$ is a Riesz basis of $L^2(\mathbb{R})$ if it is linearly independent and if there exist $A > 0, B > 0$ such that for any $f \in L^2(\mathbb{R})$ we can find a representation

$$f = \sum_n c_n e_n$$

that satisfies

$$\frac{1}{B} \|f\|^2 \leq \sum_n c_n^2 \leq \frac{1}{A} \|f\|^2$$

This "Parseval-like" energy relationship guarantees the stability of representations (convergence in norm)

using $\{e_n\}$ basis.

Proposition

A family $\{\phi(t-k)\}_{k \in \mathbb{Z}}$ is a Riesz basis of the space

$$V_0 = \overline{\text{Span}_k \{\phi(t-k)\}}$$

if and only if there exist $A > 0$, $B > 0$ such that

$$\frac{1}{B} \leq \sum_{k=-\infty}^{\infty} |\Phi(\omega - 2k\pi)|^2 \leq \frac{1}{A} \quad \forall \omega \in [-\pi, \pi]$$

where Φ denotes the FT of $\phi(t)$.

Examples

Ex. Piecewise Constant Approximations

V_j is the set of all $f \in L^2(\mathbb{R})$
such that $f(t)$ is constant on
 $t \in [k 2^{-j}, (k+1) 2^{-j})$

for each $k \in \mathbb{Z}$.

$$V_0 = \overline{\text{Span}_k \{ \phi(t-k) \}}$$

$$\phi(t) = \begin{cases} 1, & t \in [0, 1) \\ 0, & \text{o.w.} \end{cases}$$

(Haar scaling function)

Ex. Shannon Approximations
(Sinc wavelet)

V_j is defined to be the set of $f \in L^2(\mathbb{R})$ whose FT has support in the band $[-2^j\pi, 2^j\pi]$

$$V_j = \{ f \in L^2(\mathbb{R}) : F(\omega) = 0 \quad \forall |\omega| > 2^j\pi \}$$

$$V_0 = \overline{\text{span}_k \left\{ \frac{\sin \pi(t-k)}{\pi(t-k)} \right\}}$$

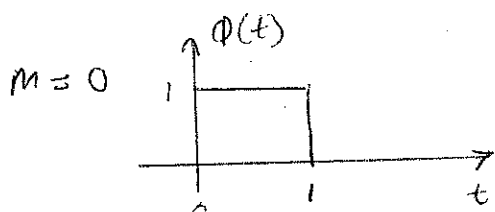
$P_{V_j} f$ is a "lowpass" approx. of f .

P_{V_j} is an ideal lowpass filter.

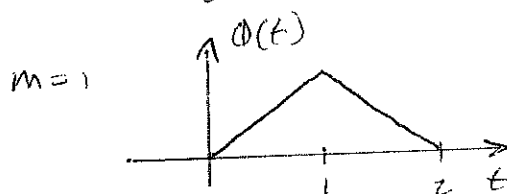
Ex. Beyond piecewise constant approximations
Spline approximation

Box spline of degree m

Convolve $\mathbb{1}_{[0,1]}$ box function
with itself m times.



piecewise constant



piecewise linear

- degree m box spline is $m-1$ times continuously differentiable
- for all $m \geq 0$, box spline basis $\{\phi(t-k)\}$ is a Riesz basis for V_0 .

The Scaling function

The family

$$\left\{ \phi_{j,k}(t) = 2^{j/2} \phi(2^j t - k) \right\}$$

is a Riesz basis of V_j for all $j \in \mathbb{Z}$

$\phi(t)$ is called the scaling function

of the associated multiresolution

analysis (MRA) :

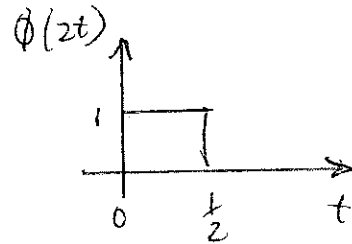
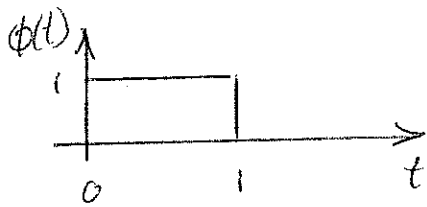
$$V_j = \overline{\text{span}_k \left\{ 2^{j/2} \phi(2^j t - k) \right\}}$$

The nesting of $V_j \supset V_{j-1}$ implies that $\phi(t) = \phi_{0,0}(t) \in V_0$ can be expressed as a linear combination of $\{\phi_{1,k}(t)\}_k$:

$$\phi(t) = \sum_{n=-\infty}^{\infty} a(n) \phi(2t-n)$$

for some sequence $\{a(n)\}_{n \in \mathbb{Z}}$.

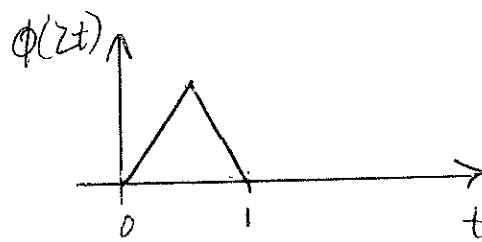
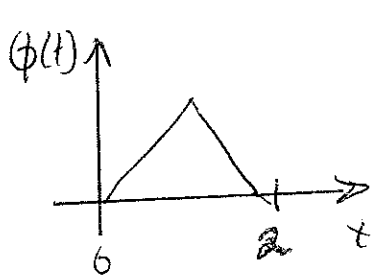
Ex. Piecewise Constant
Haar Scaling function



$$\phi(t) = \phi(2t) + \phi(2t-1)$$

$$\{a(n)\} = \{0, 0, \dots, 0, \underset{n=0}{1}, \underset{n=1}{1}, 0, 0, \dots\}$$

Ex. First order Box spline



$$\phi(t) = \frac{1}{2} \phi(2t) + \phi(2t-1) + \frac{1}{2} \phi(2t-2)$$

$$\{a(n)\} = \left\{ \dots, 0, \frac{1}{2}, 1, \frac{1}{2}, 0, \dots \right\}$$

$n = \begin{matrix} \uparrow \\ 0 \\ \uparrow \\ 1 \quad 2 \end{matrix}$

It is usual to express the relationship between $\phi(t)$ and $\{\phi(2t-n)\}$ as

$$\phi(t) = \sum_n h(n) \underbrace{\sqrt{2}}_{a(n)} \phi(2t-n)$$

since $\sqrt{2} \phi(2t-n)$ is normalized.

The coefficients $\{h(n)\}$ are called the scaling filter.

Note:

$$h(n) = \langle \phi(t), \sqrt{2} \phi(2t-n) \rangle$$

So, we see that the scaling filter $\{h(n)\}$ is intimately related to the MRA.

Under what conditions does a filter $\{h(n)\}$ correspond to a valid MRA?

Theorem (Mallat, Meyer)

Let $\phi \in L^2(\mathbb{R})$ be an integrable, orthogonal scaling function. Then the Fourier series of $h[n] = \langle \phi(t), \sqrt{2} \phi(2t-n) \rangle$ satisfies

$$\textcircled{1} \quad |H(\omega)|^2 + |H(\omega + \pi)|^2 = 2 \quad \forall \omega \in [-\pi, \pi]$$

and

$$\textcircled{2} \quad H(0) = \sqrt{2}$$

Conversely, if $H(\omega)$ is 2π -periodic continuously differentiable at $\omega=0$, satisfies $\textcircled{1}$ and $\textcircled{2}$, and if

$$\inf_{\omega \in [-\frac{\pi}{2}, \frac{\pi}{2}]} |H(\omega)| > 0$$

then

$$\Phi(\omega) = \prod_{p=1}^{\infty} \frac{H(\frac{\omega}{2^p})}{\sqrt{2}}$$

is the FT of an orthonormal scaling function $\phi \in L^2(\mathbb{R})$

(see "A Wavelet Tour of Signal Processing," S. Mallat, 1998)

This theorem shows that discrete filters satisfying certain conditions completely characterize a MRA.

Filters that satisfy ① are called quadrature (or conjugate) mirror filters.

These filters make it possible to carry out MRA directly on discrete (sampled) signals and images.

There are many variations and generalizations to this theorem that we will look at later.

MRA and Wavelets

Suppose we have a scaling function

$\phi(t)$ and the associated MRA

$$\{0\} \subset \dots \subset V_{-1} \subset V_0 \subset V_1 \subset V_2 \subset \dots \subset L^2(\mathbb{R})$$

Furthermore, assume that

$$\left\{ \phi_{j,k}(t) = 2^{j/2} \phi(2^j t - k) \right\}$$

is an orthonormal basis for

$$V_j = \text{span}_k \left\{ 2^{j/2} \phi(2^j t - k) \right\}$$

Aside: If we start with a Riesz basis that is not orthonormal, we can find a relating scaling function that does generate an orthonormal basis.

Suppose $\theta(t)$ is a scaling function and that $\left\{ \theta_{j,k}(t) = 2^{j/2} \theta(2^j t - k) \right\}$ is a Riesz basis for V_j . Then the scaling fnc $\phi(t)$ whose FT is given by

$$\underline{\Phi}(\omega) = \frac{\Theta(\omega)}{\left(\sum_{k \in \mathbb{Z}} |\Theta(\omega + 2k\pi)|^2 \right)^{1/2}}$$

generates the following orthonormal basis for V_j :

$$\left\{ \phi_{j,k}(t) = 2^{j/2} \phi(2^j t - k) \right\}_{k \in \mathbb{Z}}$$

Wavelet Subspaces

Let W_j denote the orthogonal complement of V_j in V_{j+1} .

That is W_j is the closed subspace consisting of functions in V_{j+1} that are orthogonal to V_j .

$$W_j = \{ f \in V_{j+1} : P_{V_j} f = 0 \} = \text{"wavelet subspace at resolution } 2^j \text{"}$$

With this definition V_{j+1} can be expressed as the direct sum of V_j and W_j :

$$V_{j+1} = V_j \oplus W_j \quad \left(\oplus \text{ denote } \underline{\text{direct sum}} \right)$$

Aside: A vector space X is the direct sum of two subspaces

Y and Z if every vector in $x \in X$ has a unique representation of the form $x = y + z$, where $y \in Y, z \in Z$.

In our case above, each $f \in V_{j+1}$ is uniquely represented by

$$f = P_{V_j} f + P_{W_j} f$$

The projection $P_{W_j} f$ provides the "details" of the signal that appear at resolution 2^{j+1} , but which disappear at lower resolution 2^j (coarser scale 2^{-j}).

Applying this relationship

$$V_1 = V_0 \oplus W_0$$

$$V_2 = V_1 \oplus W_1 = V_0 \oplus W_0 \oplus W_1$$

\vdots

$$L^2(\mathbb{R}) = V_0 \oplus W_0 \oplus W_1 \oplus \dots$$

Note that the initial space is arbitrary; we also have, for example,

$$L^2(\mathbb{R}) = V_6 \oplus W_6 \oplus W_7 \oplus \dots$$

$$L^2(\mathbb{R}) = V_{-5} \oplus W_{-5} \oplus W_{-4} \oplus \dots$$

or even

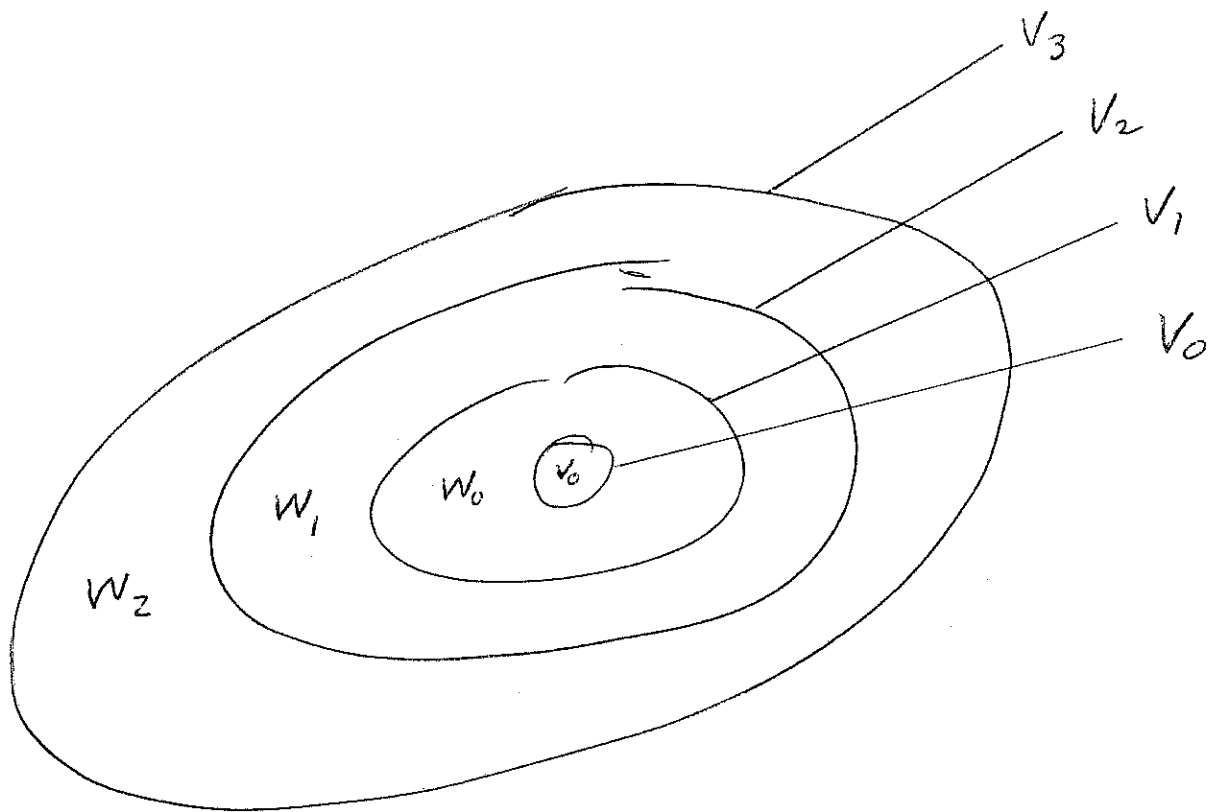
$$L^2(\mathbb{R}) = \dots \oplus W_{-1} \oplus W_0 \oplus W_1 \oplus W_2 \oplus \dots$$

eliminating the subspaces $\{V_j\}$ altogether. This shows that all the information provided by the MRA is completely contained in the wavelet subspaces $\{W_j\}$.

In practice, we usually start with a scale subspace V_j , with j chosen to represent the finest details of interest in a signal.

For example, if we sample a ^{continuous time} signal, then we have a fundamental limit on the resolution that is meaningful.

Scale and Wavelet Subspaces



Note:

$$(i) \quad W_j \perp V_j \quad \forall j$$

(That is, if $w \in W_j$ and $v \in V_j$, then $\langle w, v \rangle = 0$)

$$(ii) \quad W_i \perp W_j \quad \forall i \neq j$$

$$(iii) \quad W_j \subset V_{j+1}$$

Recall that the translates and dilates of the scaling function provide orthonormal bases for the scale spaces $\{V_j\}$.

Similarly, we would like a set of orthonormal bases for the wavelet subspaces $\{W_j\}$.

Note:

$$W_j \perp V_j \quad : \quad \text{if } w \in W_j, v \in V_j \\ \text{then } \langle w, v \rangle = 0.$$

$$W_i \perp W_j \quad i \neq j$$

$$W_j \subset V_{j+1}$$

Let $\{\psi_{j,k}\}_k$ be an orthonormal basis for W_j , $j \in \mathbb{Z}$. Then

$$\langle \psi_{j,k}, \psi_{i,l} \rangle = 0 \quad \forall k, l \in \mathbb{Z}, \quad i \neq j$$

Also note

$$\psi_{j,k} \in V_{j+1}$$

In particular,

$$\psi(t) \equiv \psi_{0,0}(t) \in V_1$$

\Rightarrow

$$\psi(t) = \sum_n \alpha_n \sqrt{2} \phi(2t-n)$$

for some $\{\alpha_n\}$

We will see later that taking

$$\alpha_n = (-1)^n h(1-n)$$

where $\{h(n)\}$ is the scaling filter associated with ϕ generates a $\psi(t)$ such that

$$\{\psi_{j,k}(t) = 2^{j/2} \psi(2^j t - k)\}_{k \in \mathbb{Z}}$$

is an orthogonal basis for W_j for all j .

The function

$$\psi(t) = \sum_n (-1)^n h(1-n) \sqrt{2} \phi(2t-n)$$

is called the prototype or mother wavelet associated with the

$$\text{MRA} \quad \dots V_{-1} \subset V_0 \subset V_1 \subset \dots$$

ex. Haar (piecewise constant) MRA

Recall

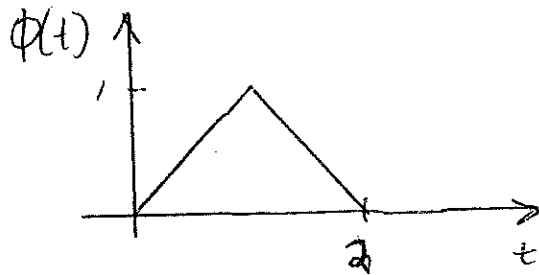
$$\phi(t) = \begin{cases} 1 & t \in [0, 1) \\ 0 & \text{o.w.} \end{cases}$$

$$h(n) = \left\{ 0, \dots, 0, \underset{h=0}{\frac{1}{\sqrt{2}}}, \underset{h=1}{\frac{1}{\sqrt{2}}}, 0, \dots \right\}$$

\Rightarrow

$$\begin{aligned} \psi(t) &= \frac{1}{\sqrt{2}} \cdot \sqrt{2} \phi(2t) - \frac{1}{\sqrt{2}} \sqrt{2} \phi(2t-1) \\ &= \phi(2t) - \phi(2t-1) \end{aligned}$$

Ex. First order Box Spline

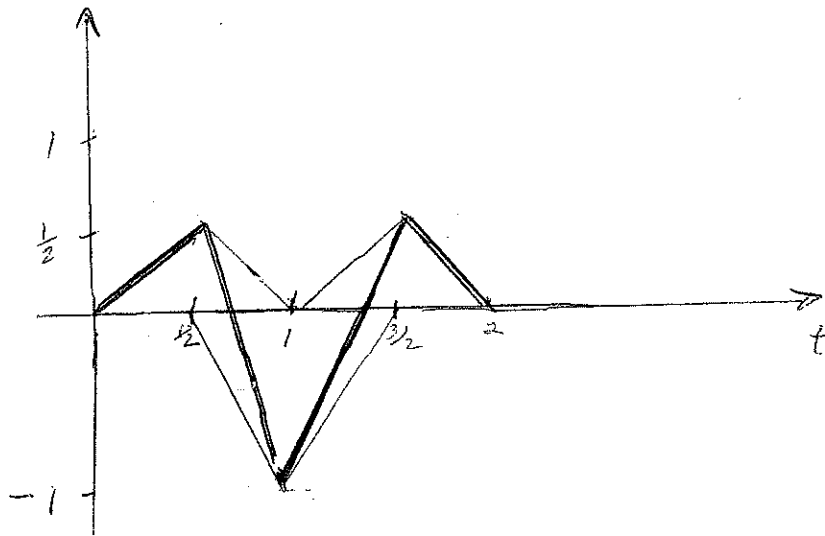


$$\{h(n)\} = \left\{ \dots, 0, \frac{1}{2\sqrt{2}}, \frac{1}{\sqrt{2}}, \frac{1}{2\sqrt{2}}, 0, \dots \right\}$$

$\begin{matrix} | & | & | \\ n=0 & n=1 & n=2 \end{matrix}$

\Rightarrow

$$\psi(t) = \frac{1}{2} \phi(2t) - \phi(2t-1) + \frac{1}{2} \phi(2t-2)$$



Caution: This is not an orthogonal system.

Wavelet Representations

$$V_0 \oplus W_0 \oplus W_1 \oplus \dots = L^2(\mathbb{R})$$

Orthogonality

\Rightarrow

$$f = P_{V_0} f + P_{W_0} f + P_{W_1} f + \dots$$

If $\{\phi(t-k)\}_k$ is an o.n. basis for V_0
and $\{2^{j/2}\psi(2^j t - k)\}_k$ is an o.n. basis for W_j
 $j \geq 0$

then we can write

$$f(t) = \sum_{k=-\infty}^{\infty} c(k) \phi(t-k) + \sum_{j \geq 0} \sum_{k=-\infty}^{\infty} d_j(k) 2^{j/2} \psi(2^j t - k)$$

where

$$c(k) = \langle f, \phi(t-k) \rangle$$

$$d_j(k) = \langle f, 2^{j/2} \psi(2^j t - k) \rangle$$

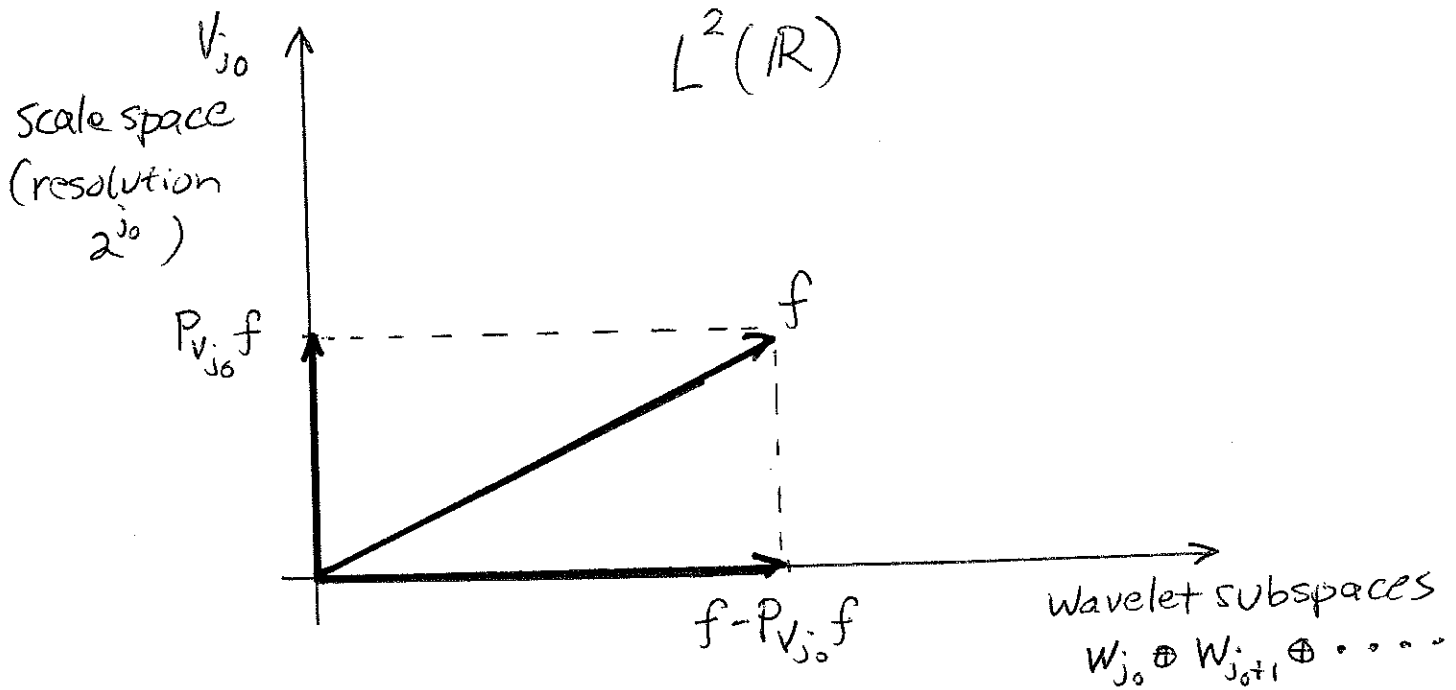
More generally, we can start at any scale 2^{j_0} and write

$$f(t) = \sum_k c_{j_0}(k) 2^{j_0/2} \phi(2^{j_0}t - k) + \sum_k \sum_{j=j_0}^{\infty} d_j(k) 2^{j/2} \psi(2^j t - k)$$

The coefficients $\{c_{j_0}(k)\}_k$ applied to the scaling basis functions $\{2^{j_0/2} \phi(2^{j_0}t - k)\}_k$ produce the low resolution (coarse scale) approximation of f , corresponding to the projection of f onto the subspace V_{j_0} .

$\{d_j(k)\}_{j,k}$ and $\{2^{j/2} \psi(2^j t - k)\}_{k, j \geq j_0}$ provide the high resolution details of the signal.

Geometrically,



The coefficients

$$\{c_{j_0}(k)\}_k, \{d_j(k)\}_k, j \geq j_0$$

are called the

discrete wavelet transform (DWT)

of f .

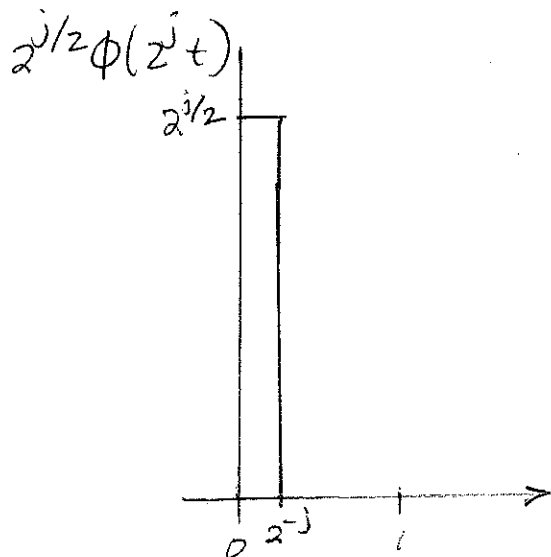
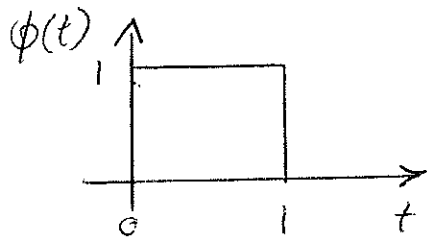
Connection to DSP

At high resolutions, the scaling functions are similar to Dirac delta functions (assuming $\phi(t)$ is localized and well-behaved)

That is,

$$2^{j/2} \phi(2^j t) \rightsquigarrow \delta(t) \quad \text{as } j \rightarrow \infty$$

Ex. Haar scaling function



So, for j sufficiently large
we have

$$\begin{aligned}c_j(k) &= \langle f, \phi_{j,k} \rangle \\&= \int_{-\infty}^{\infty} f(t) 2^{j/2} \phi(2^j t - k) dt \\&\approx \int_{-\infty}^{\infty} f(t) \delta(t - k 2^{-j}) dt \\&= f(k 2^{-j})\end{aligned}$$

In other words, the scaling coefficients
are approximately equal to signal
samples at a sampling rate of

$$T = 2^{-j} \quad (\text{sampling frequency } \omega_s = 2\pi 2^j)$$

Computing the DWT

Mallat's Fast Wavelet Transform (FWT) algorithm

- ① Assume an initial set of scaling coefficients $\{c_J(k)\}_k$, representing an approximation $f_J = P_{V_j} f$ to a signal f at a certain scale related to the sampling period $T = 2^{-J}$.
($\approx f$ assuming J sufficiently large)
- ② The wavelet and scaling coefficients at coarser scales, $j < J$, are then computed recursively using the (lowpass) scaling filter $\{h(n)\}_n$ and (highpass) wavelet filter $\{h_1(n) = (-1)^n h(1-n)\}_n$

$$\textcircled{a} \quad c_j(k) = \langle f, 2^{j/2} \phi(2^j t - k) \rangle$$

$$= \sum_n h(n-2k) c_{j+1}(n)$$

$$\textcircled{b} \quad d_j(k) = \langle f, 2^{j/2} \psi(2^j t - k) \rangle$$

$$= \sum_n h_1(n-2k) c_{j+1}(n)$$

for $j = J-1, J-2, \dots$

\textcircled{a} lowpass filter c_{j+1} to obtain lower resolution approximation

\textcircled{b} highpass filter c_{j+1} to obtain details in c_{j+1} but not in c_j .

Decimation: The filters are shifted by $2k$ (rather than k) so that only even indexed terms (at filter outputs) are retained. This eliminates redundant information in full sequence outputs $\sum_n h(n-k) c_{j+1}(n)$ and $\sum_n h_1(n-k) c_{j+1}(n)$

With these coefficients (computed using simple digital filters!) we have the representation

$$P_{V_J} f = \sum_{k=-\infty}^{\infty} c_{j_0}(k) 2^{j_0/2} \phi(2^{j_0/2} t - k) + \sum_{k=-\infty}^{\infty} \sum_{j=j_0}^{J-1} d_j(k) 2^{j/2} \psi(2^j t - k)$$

↑
finite sum!

Moreover, if f is of finite time duration, then the sums over k are also finite and hence $P_{V_J} f$ is completely determined by a handful of numbers (scaling and wavelet coefficients)

Note: This opens the door to a whole new world of DSP. Instead of processing signal samples, we can analyze and process a signal using its DWT!

Ex: Haar Analysis

$$h(n) = \{ \dots, 0, \frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, 0, \dots \}$$

$$h_1(n) = \{ \dots, 0, \frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}, 0, \dots \}$$

Begin with

$$\{c_j(k)\}_k$$

for $j < J$,

$$c_j(k) = \frac{1}{\sqrt{2}} c_{j+1}(2k) + \frac{1}{\sqrt{2}} c_{j+1}(2k+1)$$

$$d_j(k) = \frac{1}{\sqrt{2}} c_{j+1}(2k) - \frac{1}{\sqrt{2}} c_{j+1}(2k+1)$$

$$\{c_j(k)\} = \text{local sums of } \{c_{j+1}(k)\}$$

$$\{d_j(k)\} = \text{local differences of } \{c_{j+1}(k)\}$$

Note: In this special case (Haar) we have

$$c_{j+1}(2k) = \frac{1}{\sqrt{2}} c_j(k) + \frac{1}{\sqrt{2}} d_j(k)$$

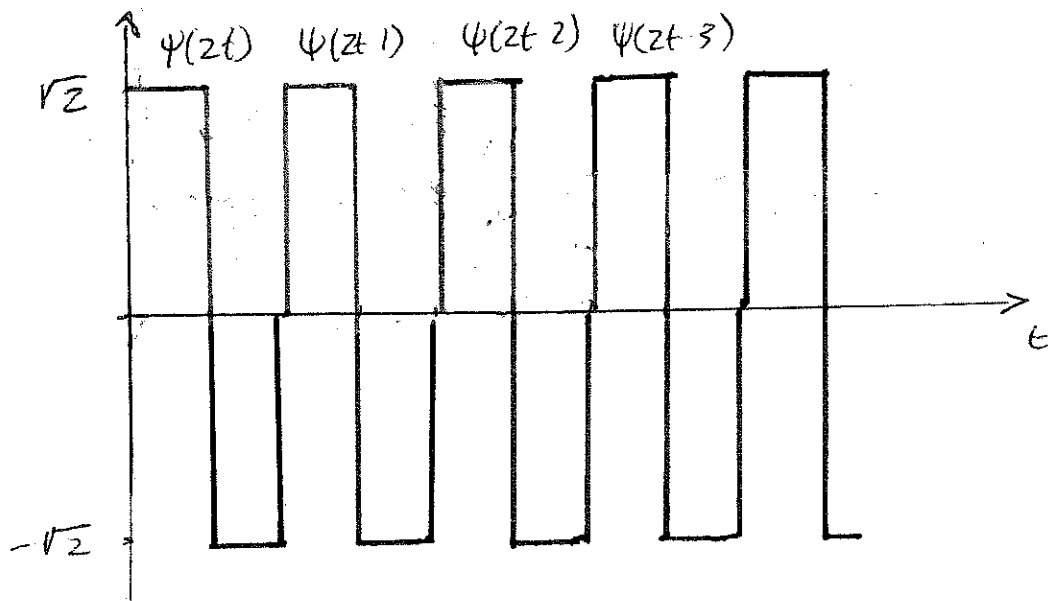
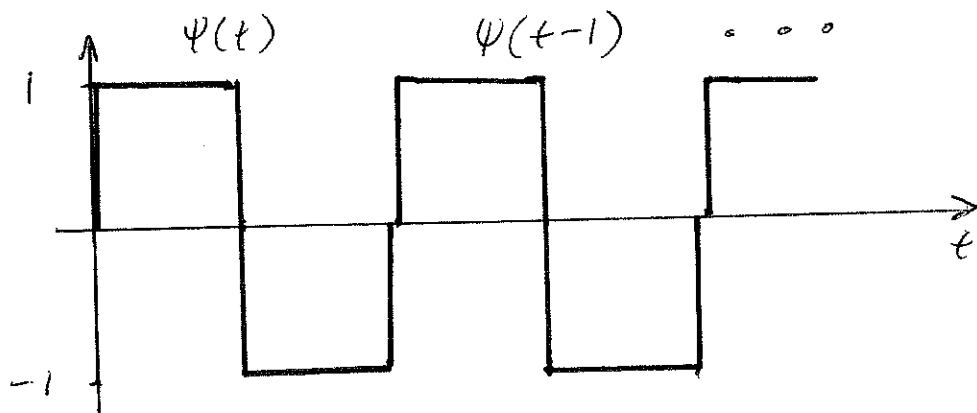
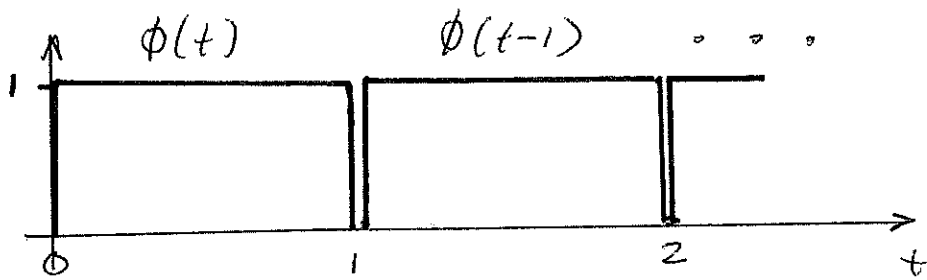
$$c_{j+1}(2k+1) = \frac{1}{\sqrt{2}} c_j(k) - \frac{1}{\sqrt{2}} d_j(k)$$

Which gives us a simple reconstruction (synthesis) procedure!

Associated Scaling and Wavelet Functions

Take $j_0 = 0$, for simplicity.

$$P_{V_j} f = \sum_k c_0(k) \phi(t-k) + \sum_k \sum_{j=0}^{J-1} d_j(k) 2^{j/2} \psi(2^j t - k)$$



Multiresolution Analysis of $L^2(\mathbb{R})$

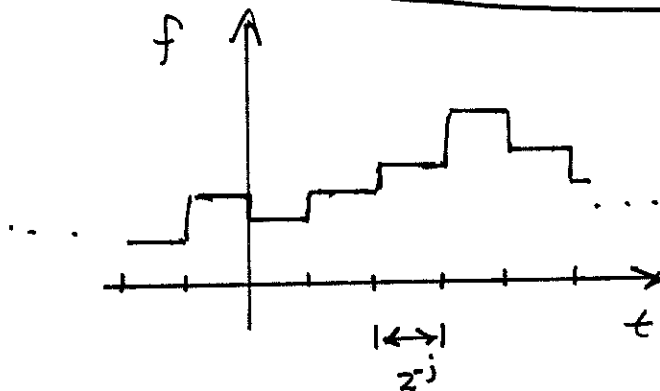
Main Idea: Decompose $L^2(\mathbb{R})$ into a sequence of nested subspaces, each consisting of functions with successively finer "detail" and structure (i.e., higher resolution).

Basic Properties:

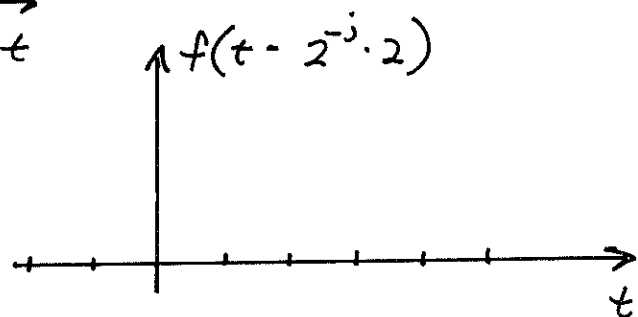
①

$$f \in V_j \iff f(t - 2^{-j}k) \in V_j$$

for all j, k integers.



Shift f in time
by $2^{-j}k$



②

$$V_{j+1} \supset V_j \quad \text{for all } j$$

Let $f \in V_j$ and let V_j be Haar subspace.

The f is piecewise constant on intervals $[kz^{-j}, (k+1)z^{-j})$, k

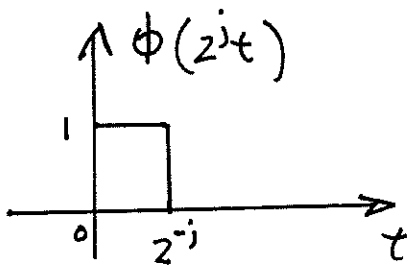
$\Rightarrow f$ is constant on intervals $[kz^{-(j+1)}, (k+1)z^{-(j+1)})$, $k \in \mathbb{Z}$

$\Rightarrow f \in V_{j+1}$.

Another view:

$$V_j \equiv \text{span} \left(\left\{ \phi(z^j t - k) \right\}_{k \in \mathbb{Z}} \right)$$

where



i.e., there exists a func $\phi(t)$ such that $\{\phi(z^j t - k)\}$ is a basis for V_j

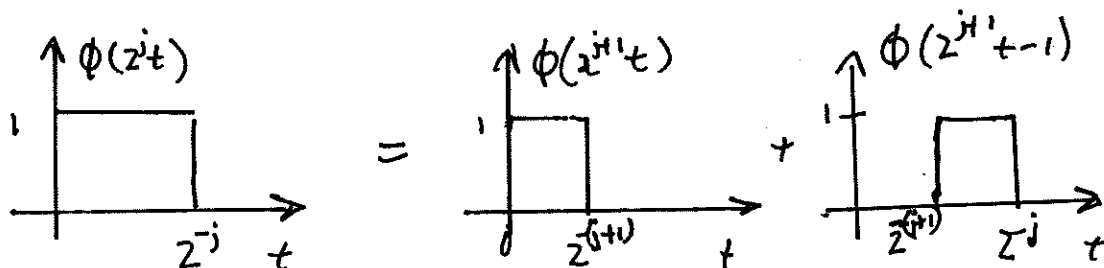
$$f \in V_j \Rightarrow f = \sum_{k=-\infty}^{\infty} \alpha_k \phi(z^j t - k)$$

$$V_{j+1} \equiv \text{span} \left(\left\{ \phi(z^{j+1} t - k) \right\}_{k \in \mathbb{Z}} \right)$$

In particular,

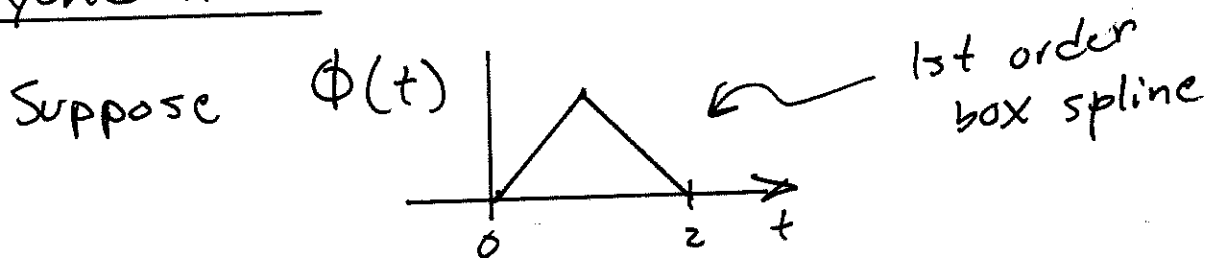
$$\phi(2^j t - k) \in V_{j+1}$$

$$\phi(2^j t) = \phi(2^{j+1} t) + \phi(2^{j+1} t - 1)$$

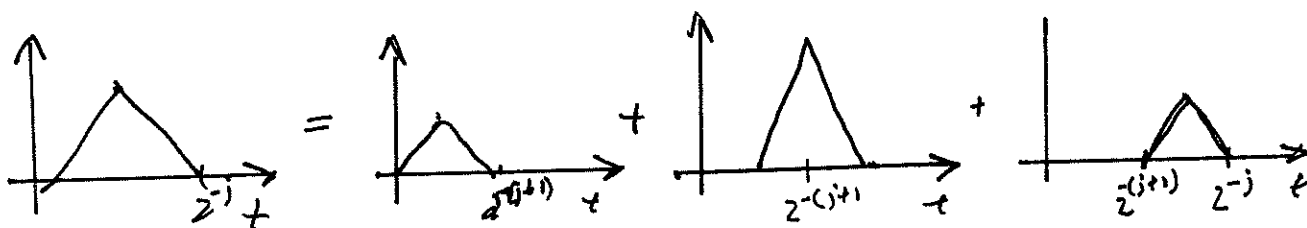


$$\Rightarrow V_j \subset V_{j+1}$$

Beyond Haar:



$$\phi(2^j t) = \frac{1}{2} \phi(2^{j+1} t) + \phi(2^{j+1} t - 1) + \frac{1}{2} \phi(2^{j+1} t - 2)$$



$$\Rightarrow V_j = \text{span}(\{\phi(2^j t - k)\})$$

$$\subset V_{j+1} = \text{span}(\{\phi(2^{j+1} t - k)\})$$

$$\textcircled{3} \quad f \in V_j \iff f(zt) \in V_{j+1} \text{ for all } j$$

$$f \in V_j \implies f(t) = \sum_k \alpha_k \phi(2^j t - k)$$

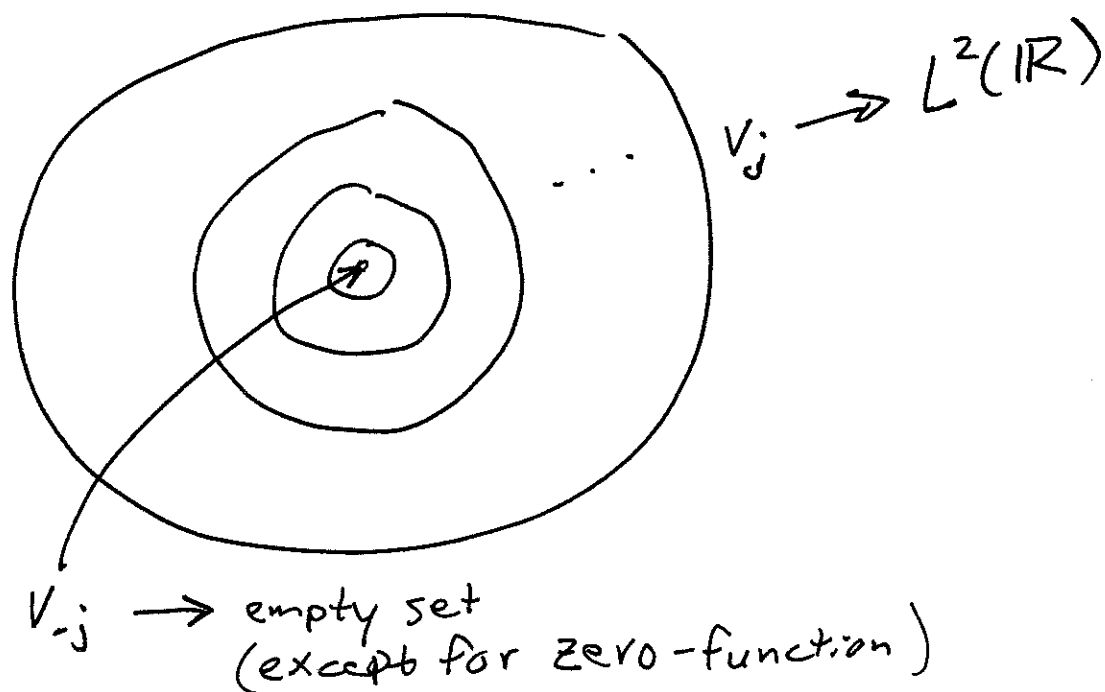
$$\implies f(zt) = \sum_k \alpha_k \phi(2^j (zt) - k)$$

$$= \sum_k \alpha_k \phi(2^{j+1} t - k)$$

$$\implies f(zt) \in V_{j+1}.$$

$$\textcircled{4} \quad V_{-\infty} = \lim_{j \rightarrow \infty} V_{-j} = \{0\}$$

$$\textcircled{5} \quad V_{\infty} = \lim_{j \rightarrow \infty} V_j = L^2(\mathbb{R})$$



Key Equation:

$$V_j \subset V_{j+1}$$

scaling
equation.

$$\Rightarrow \boxed{2^{j/2} \phi(2^j t) = \sum_{n=-\infty}^{\infty} h(n) 2^{(j+1)/2} \phi(2^{j+1} t - n)}$$

There exists a sequence $\{h(n)\}$
relating basis functions for V_j
to basis for V_{j+1} .

Note that if the basis functions
are orthogonal (e.g., Haar), then

$$h(n) = \langle 2^{j/2} \phi(2^j t), 2^{(j+1)/2} \phi(2^{j+1} t - n) \rangle$$

Key Theorem:

Let $\phi \in L^2(\mathbb{R})$, $\{\phi(t-n)\}_{n \in \mathbb{Z}}$ an orthogonal basis for $V_0 \subset L^2(\mathbb{R})$. Then, to ensure a valid multiresolution analysis, the sequence

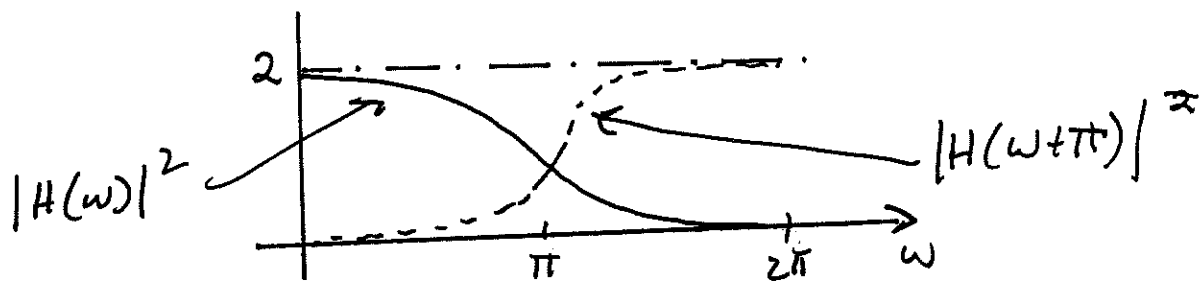
$$h(n) = \langle \phi(t), \sqrt{2} \phi(2t-n) \rangle$$

must satisfy

$$\textcircled{1} \quad |H(\omega)|^2 + |H(\omega+\pi)|^2 = 2 \quad \text{for } \omega \in [0, 2\pi]$$

$$\textcircled{2} \quad H(0) = \sqrt{2},$$

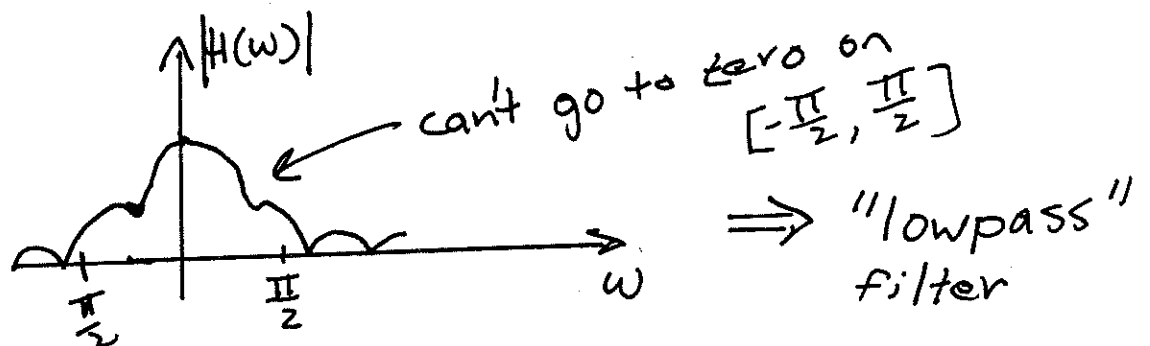
$$\text{where } H(\omega) = \sum_n h(n) e^{-j\omega n}$$



Conversely, if $H(\omega)$ is continuously differentiable at $\omega=0$, satisfies

① and ②, and

$$\inf_{\omega \in [-\frac{\pi}{2}, \frac{\pi}{2}]} |H(\omega)| > 0$$



then

$$\Phi(\omega) = \prod_{p=1}^{\infty} \frac{H\left(\frac{\omega}{2^p}\right)}{\sqrt{2}}$$

produces an orthonormal scaling function

$$\phi(t) = \int_{-\infty}^{\infty} \Phi(\omega) e^{j\omega t} d\omega$$

proof: see Mallat
 pp. 229 - 234

