

Subspace Analysis Methods for Line Spectra

In applications such as communications, radar, sonar, and geophysics, the signals of interest are often well described by the following sinusoidal model:

$$x(n) = \sum_{i=1}^P \alpha_i e^{j(2\pi f_i n + \phi_i)}$$

Where $x(n)$ is a noise-free, complex-valued sinusoidal process with unknown amplitudes $\{\alpha_i\}$ and frequencies $\{f_i\}$ and statistically independent, random phases $\{\phi_i\}$, uniformly distributed on $[0, 2\pi)$. We measure / observe a noisy version of x :

$$y(n) = x(n) + w(n)$$

↑
additive observation
noise

The noise $\{w(n)\}$ is assumed to be (complex-valued) circular white noise.

The covariance function and power spectral density of the noisy signal y can be calculated as follows.

Because the phases are iid, we have

$$E\left[e^{j\phi_k} e^{-j\phi_l}\right] = 1, \quad k=l$$

and

$$\begin{aligned} E\left[e^{j\phi_k} e^{-j\phi_l}\right] &= E\left[e^{j\phi_k}\right] \cdot E\left[e^{-j\phi_l}\right] \\ &= \int_0^{2\pi} \frac{e^{j\phi_k}}{2\pi} d\phi_k \int_0^{2\pi} \frac{e^{-j\phi_l}}{2\pi} d\phi_l \\ &= 0, \quad k \neq l \end{aligned}$$

Thus,

$$E\left[e^{j\phi_k} e^{-j\phi_l}\right] = \delta(k-l)$$

Let $x_k(n) = \alpha_k e^{j(2\pi f_k n - \phi_k)}$. Then

$$E \left[x_k(n) x_k^*(n-m) \right] = \alpha_k^2 e^{j 2\pi f_k m} \delta(k-l)$$

and

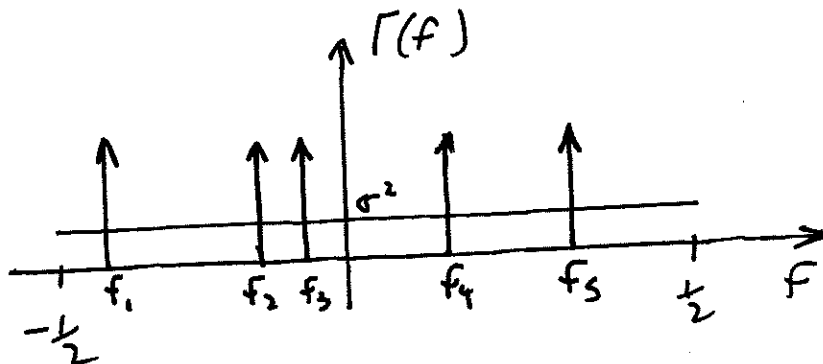
$$E \left[y(n) y^*(n-m) \right] = \sum_{i=1}^P \alpha_i^2 e^{j 2\pi f_i m} + \sigma^2 \delta(m)$$

\Rightarrow

$$Y(m) = \sum_{i=1}^P \alpha_i^2 e^{j 2\pi f_i m} + \sigma^2 \delta(m)$$

The power spectral density is the DTFT of γ :

$$\Gamma(f) = \sum_{i=1}^P \alpha_i^2 \delta(f - f_i) + \sigma^2$$



Because the spectrum consists of Dirac impulses, $\Gamma(f)$ is called a line spectrum.

Notice that spectral analysis, in this case, reduces to a parameter estimation problem:

From observations $y(n)$, $n = 0, \dots, N-1$ estimate $\{\alpha_i, f_i\}$ (and possibly p).

Notice also that if p and $\{f_i\}$ are known, then estimation of $\{\alpha_i\}$ is a simple linear regression problem:

$$\begin{bmatrix} y(0) \\ y(1) \\ \vdots \\ y(N-1) \end{bmatrix} = \begin{bmatrix} 1 & \dots & 1 \\ e^{j2\pi f_1} & \dots & e^{j2\pi f_p} \\ \vdots & & \vdots \\ e^{j2\pi f_1(N-1)} & \dots & e^{j2\pi f_p(N-1)} \end{bmatrix} \begin{bmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_p \end{bmatrix} + \begin{bmatrix} w(0) \\ w(1) \\ \vdots \\ w(N-1) \end{bmatrix}$$

Where $\{\beta_i \equiv \alpha_i e^{j\phi_i}\}$. $\hat{\beta}$ given by LS solution.



Jointly estimating $\{\beta_i, f_i\}$ is a highly nonlinear regression problem. An intuitively appealing approach is to estimate $\{\beta_i, f_i\}$ as the minimizers of

$$C(\{\beta_i, f_i\}) = \sum_{n=0}^{N-1} \left| y(n) - \sum_{i=1}^D \beta_i e^{j2\pi f_i n} \right|^2.$$

This criterion is called nonlinear least squares.

Unfortunately, the minimization is very complicated and requires sophisticated numerical methods. Moreover, $C(\{\beta_i, f_i\})$ has a multimodal surface and there is no guarantee that numerical methods will produce the least squares result.

So, rather than considering this joint optimization, we will focus on the problem of frequency estimation.

That is, we'll first estimate $\{f_i\}$, then plug them into $(*)$ and solve the linear equations for $\{\beta_i\}$.

Covariance Matrix Model

Let $M < N$

$$\underline{s}_i = [1 \ e^{-j2\pi f_i} \ \dots \ e^{-j2\pi f_i \cdot (M-1)}]^T$$

$i = 1, \dots, P \leq M$

and

$$\underline{y} = [y(n) \ y(n-1) \ \dots \ y(n-M+1)]^T$$

$$\begin{aligned}\underline{y} &= [\underline{s}_1 \ \dots \ \underline{s}_P] \underline{\beta} + \underline{w} \\ &= \sum_{i=1}^P \beta_i \underline{s}_i + \underline{w}\end{aligned}$$

The covariance matrix of \underline{y} is

$$\begin{aligned}\underline{R} &= E[\underline{y} \underline{y}^*] \\ &= \sum_{k=1}^P \sum_{l=1}^P E[\beta_k \beta_l^*] \underline{s}_k \underline{s}_l^H + E[\underline{w} \underline{w}^*] \\ &= \sum_{k=1}^P |\alpha_k|^2 \underline{s}_k \underline{s}_k^H + \sigma^2 \underline{I}\end{aligned}$$

Let $\underline{S} = [\underline{s}_1 \dots \underline{s}_p]$, then

$$\underline{R} = \underline{S} \underline{P} \underline{S}^H + \sigma^2 \underline{I}$$

Where $\underline{P} = \begin{bmatrix} |\alpha_1|^2 & & 0 \\ & \ddots & \\ 0 & & |\alpha_p|^2 \end{bmatrix}$

Note that

$$\underline{S} \underline{P} \underline{S}^H \text{ is } M \times M$$

but its rank is $p \leq M$.

If $p < M$, then smallest

$M-p$ eigenvalues of \underline{R} are equal to σ^2 . As we'll see

shortly, the eigenstructure

of \underline{R} contains complete information about the frequencies $\{f_i\}$.

Pisarenko and MUSIC methods

The Multiple Signal Characterization (MUSIC) method (Schmidt 1979, Bienvenu 1979) and Pisarenko's method (Pisarenko 1973, a special case of MUSIC) are derived from the covariance model with $p < N$.

Let $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_M$ denote the eigenvalues of \underline{R} and let

$\{\underline{v}_1, \dots, \underline{v}_M\}$ denote the corresponding orthonormal eigenvectors.

Since $\underline{S} \underline{P} \underline{S}^H$ has rank p , it follows that it has p strictly positive eigenvalues (the remaining $M-p$ are zero).

Let $\{\tilde{\lambda}_i\}_{i=1}^p$ denote the positive eigenvalues of $\underline{S} \underline{P} \underline{S}^H$.

Let $\{\underline{u}_1, \dots, \underline{u}_p\}$ be the eigenvectors associated with the p non-zero eigenvalues of $\underline{S}\underline{P}\underline{S}^H$. Consider

$$\begin{aligned}\underline{u}_i^H \underline{R} \underline{u}_i &= \underline{u}_i^H \underline{S}\underline{P}\underline{S}^H \underline{u}_i + \sigma^2 \underline{u}_i^H \underline{I} \underline{u}_i \\ &= \tilde{\lambda}_i + \sigma^2\end{aligned}$$

Also,

$$\begin{aligned}\underline{R} \underline{u}_i &= \tilde{\lambda}_i \underline{u}_i + \sigma^2 \underline{u}_i \\ &= (\tilde{\lambda}_i + \sigma^2) \underline{u}_i.\end{aligned}$$

Thus, we see that $\{\underline{u}_i\}_{i=1}^p$ are orthonormal eigenvectors of \underline{R} with eigenvalues $\lambda_i = \tilde{\lambda}_i + \sigma^2$.

Let us make the identification

$$\{\underline{v}_1, \dots, \underline{v}_p\} \equiv \{\underline{u}_1, \dots, \underline{u}_p\}.$$

Let $\underline{G} = [\underline{v}_{M-p}, \dots, \underline{v}_M]$.

Then, from $\textcircled{\#}$, we have

$$\underline{S}^H \underline{G} = \underline{0}$$

Recall that

$$\underline{S} = \underline{S}(\{f_i\}_{i=1}^D)$$

$$= \begin{bmatrix} e^{j2\pi f_1} & \dots & e^{j2\pi f_p} \\ \vdots & & \vdots \\ e^{j2\pi f_1(M-1)} & & e^{j2\pi f_p(M-1)} \end{bmatrix}$$

$$= [\underline{S}(f_1) \dots \underline{S}(f_2)]$$

where $\underline{S}(f_i) = \begin{bmatrix} e^{j2\pi f_i} \\ \vdots \\ e^{j2\pi f_i(M-1)} \end{bmatrix}$

Now, since all of \underline{R} 's eigenvectors are orthonormal, we have

$$\underline{V}_k^H \underline{V}_l = \delta(k-l)$$

and in particular for $k=1, \dots, P$ and $l=M-P, \dots, M$

$$\underline{V}_k^H \underline{V}_l = \underline{u}_k^H \underline{V}_l = 0.$$

Therefore

$$\underline{V}_i^H \underline{S} \underline{P} \underline{S}^H \underline{V}_i = 0, \quad i=M-P, \dots, M \quad \textcircled{\#}$$

and

$$\underline{R} \underline{V}_i = \sigma^2 \underline{V}_i, \quad i=M-P, \dots, M$$

$\text{Span}(\{ \underline{V}_i \}_{i=1}^P) \equiv \text{"signal + noise" subspace}$
$\text{Span}(\{ \underline{V}_i \}_{i=M-P}^M) \equiv \text{"noise-only" subspace}$

From $\underline{S}^H \underline{G} = 0$ we obtain
the following key result.

The true frequency values $\{f_i\}_{i=1}^P$
are the only solutions of the
equation

$$\underline{S}^H(f) \underline{G} \underline{G}^H \underline{S}(f) = 0$$

Note: we require that $M > P$
(i.e., we have a noise-only subspace)

Using this result, we can
derive the MUSIC algorithm.

MUSIC

Data $y(n), n=1, \dots, N$

Step 1: Compute the sample covariance matrix

$$\hat{\underline{R}} = \frac{1}{N} \sum_{n=M}^N \underline{y}_n \underline{y}_n^H$$

where $\underline{y}_n = [y(n), y(n-1), \dots, y(n-M+1)]^T$

Step 2a: (Spectral Music) (Schmidt '79)

Determine frequency estimates as the locations of the P highest peaks of

$$\frac{1}{\underline{s}^H(f) \hat{\underline{G}} \hat{\underline{G}}^H \underline{s}(f)} \quad f \in [-\frac{1}{2}, \frac{1}{2}]$$

- OR - $\hat{\underline{G}}$ defined similarly to \underline{G} , but based on eigenvectors of $\hat{\underline{R}}$

Step 2b: (Root Music) (Barabell '83)

Determine frequency estimates as the angular positions of the P (pairs of reciprocal) roots of

$$\underline{s}(z^{-1}) \hat{\underline{G}} \hat{\underline{G}}^H \underline{s}(z^{-1}) = 0$$

which are closest to the unit circle.

$$\underline{s}(z) = [1 \ z^{-1} \ \dots \ z^{-(M-1)}]^T$$

MUSIC requires a noise-only

subspace in order to work.

Therefore, the minimum value for M is $M = p + 1$ (1-dim noise-only subspace).

For $M = p + 1$, the MUSIC algorithm reduces to the Pisarenko method.

In this case, we use the Step 2b approach which boils down to the degree p polynomial equation

$$\underline{S}^T(\underline{z}^{-1}) \hat{\underline{V}}_M = 0$$

where $\hat{\underline{V}}_M$ is the eigenvector associated with the smallest eigenvalue of $\hat{\underline{R}}$.

Ex. $y(n) = \sum_{i=1}^4 \alpha_i e^{j(2\pi f_i n + \phi_i)} + w(n)$

$\alpha_i = 1, i=1, 2, 3, 4$

$\{w(n)\}$ zero-mean white noise

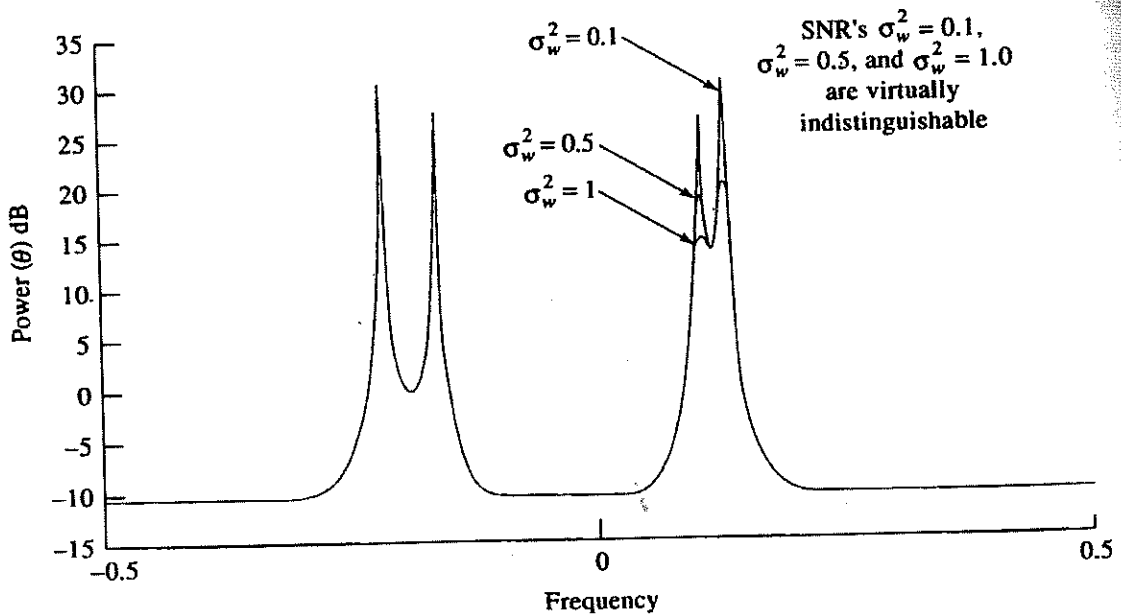
$\{\phi_i\}$ iid uniform $(0, 2\pi)$

$f_1 = -0.222, f_2 = -0.166, f_3 = 0.10, f_4 = 0.1222$

$N = 1024$

MUSIC "pseudospectrum"

$$\Gamma_{\text{music}}(f) = \frac{1}{\sum_{i=p+1}^M |\underline{s}^H(f) \underline{v}_i|^2}$$



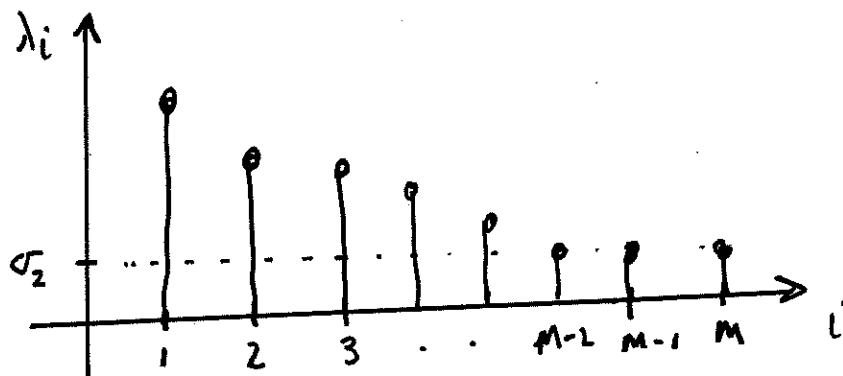
Model Order Selection

Recall that if the signal y consists of p sinusoids in white noise, then the covariance matrix has eigenvalues

$$\{\lambda_i\} = \{\tilde{\lambda}_i + \sigma^2\} \quad i=1, \dots, p$$

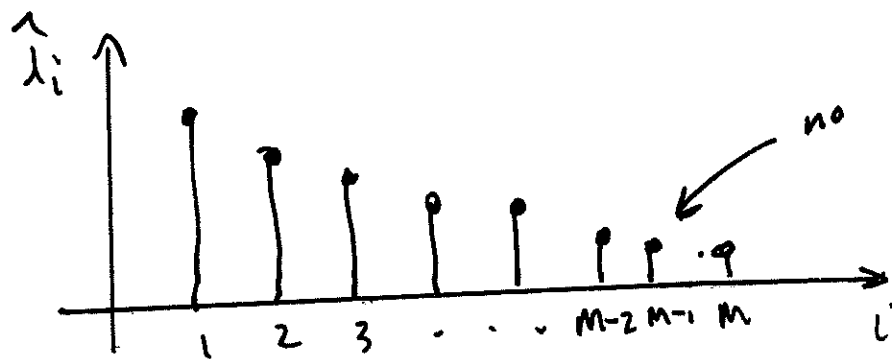
$$\{\lambda_i\} = \{\sigma^2\} \quad i=p+1, \dots, M$$

Thus, if we order the eigenvalues $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_M$ we have



In this case, we have $p = M-3$.

Now, of course we only have the estimated covariance matrix $\hat{\underline{R}}$, and thus noisy estimates of the true eigenvalues.



How do we decide which correspond to signal and noise?

No sharp cut-off in general.

Minimum Description Length Criterion

Wax & Kailath (1985)

$$\text{MDL}(p) = -\log \left(\frac{r(p)}{q(p)} \right)^N + e(p)$$

$$r(p) = \prod_{i=p+1}^M \hat{\lambda}_i \quad p = 0, 1, \dots, M-1$$

$$q(p) = \left[\frac{1}{M-p} \sum_{i=p+1}^M \hat{\lambda}_i \right]^{M-p}$$

where
 $\hat{\lambda}_1 \geq \hat{\lambda}_2 \geq \dots \geq \hat{\lambda}_M$
are eigenvalues
of \hat{R} .

$$e(p) = \frac{1}{2} p (2M-p) \log N$$

$$\hat{p} = \arg \min_p \text{MDL}(p)$$

Interpretation:

$\frac{r(p)}{q(p)}$ measures how close the "tail" eigenvalues are to their average

$e(p)$ measures the "complexity" of using p sinusoidal components, given N measurements