

ECE 830 Fall 2011 Statistical Signal Processing

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Lecture 13: Parameter Estimation

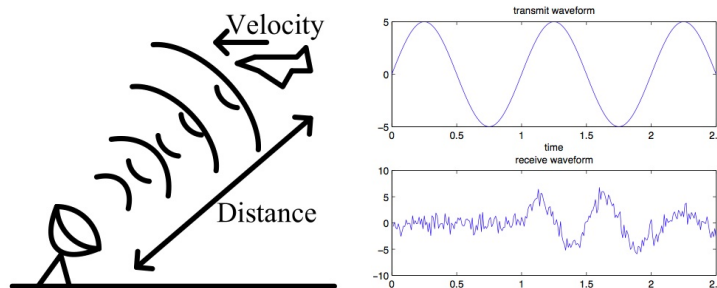
We observe $X \sim p(x|\theta), \theta \in \Theta$, and the goal is to determine the θ that produced X .

1 Generative Model:

Select $\theta \in \Theta \rightarrow$ randomly generate $X \sim p(x|\theta)$, i.e. “draw X from $p(x|\theta)$ ”

- Estimator
Observe $X \sim p(x|\theta) \xrightarrow{\text{infer}} \theta \in \Theta$
Estimation is a sort of “inverse” problem

2 Radar Example:



Radar is used to estimate the distance of an object

The received waveform is time-dilated and shifted version of original waveform $g(t)$ plus noise

$$x(t) = g(\alpha t - \tau) + w(t) .$$

The parameter of interest is $\theta = \begin{bmatrix} \alpha \\ \tau \end{bmatrix}$, where α is related to velocity / Doppler shift, τ is related to distance

$$\tau = \frac{2d}{c}, c = \text{speed of light}$$

$$x \rightarrow \hat{\tau} \rightarrow \hat{d} = \frac{c\hat{\tau}}{2}$$

3 Imaging Example:

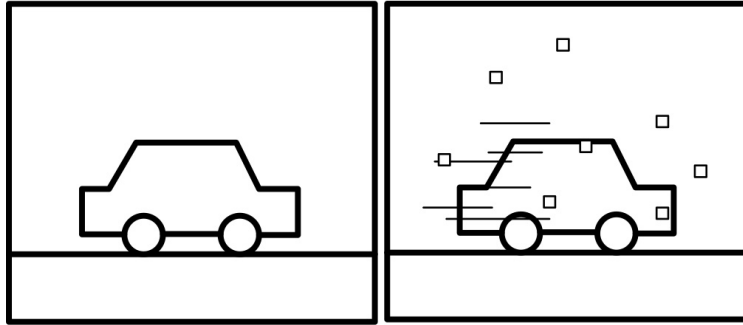


Image processing can involve complicated estimation problems. For example, suppose we observe a moving object with noise. This image is blurry and noisy and our goal is to “restore” this image by deblurring and denoising.

We can model the observed image as

$$x = \underbrace{h * \theta}_{\text{motion blur (convolution)}} + \underbrace{w}_{\text{noise}}$$

where the parameter of interest θ is the ideal image.

- Vector model:
 $X = H\theta + w, w \sim N(0, \sigma^2 I)$
 $X \sim N(H\theta, \sigma^2 I)$
- Estimator:
 $\hat{\theta} = f(x)$, a function of x

4 Basic Ingredients of Estimation Theory

- Observation model:
 $X \sim p(x|\theta), \theta \in \Theta, x \in \mathcal{X}$
- Estimator:
 $\hat{\theta} : \mathcal{X} \rightarrow \Theta$, a mapping from \mathcal{X} to Θ
- Loss/Error Function:
 $\ell : \Theta \times \Theta \rightarrow \mathbb{R}^+$
 $\ell(\theta, \hat{\theta})$ measures proximity of $\hat{\theta}$ to θ

- Risk (Average/Expected Loss:)

$$\begin{aligned} R(\theta, \hat{\theta}) &= \mathbb{E}[\ell(\theta, \hat{\theta}(x))] \\ &= \int_{\mathcal{X}} \ell(\theta, \hat{\theta}(x)) p(x|\theta) dx \end{aligned}$$

5 Optimal Estimator:

$$\hat{\theta}_{opt} = \arg \min_{\hat{\theta}: \mathcal{X} \rightarrow \Theta} R(\theta, \hat{\theta})$$

$\hat{\theta}_{opt}$ is optimal with respect to chosen loss function.

- Squared Error (ℓ_2 loss)

$$\ell(\theta, \hat{\theta}) = \|\theta - \hat{\theta}\|_2^2 = \sum_{i=1}^n (\theta_i - \hat{\theta}_i)^2$$

- Absolute Error (ℓ_1 loss)

$$\ell(\theta, \hat{\theta}) = \|\theta - \hat{\theta}\|_1 = \sum_{i=1}^n |\theta_i - \hat{\theta}_i|$$

penalize large errors less than ℓ_2

- 0/1 loss

$$\ell(\theta, \hat{\theta}) = \begin{cases} 1 & \hat{\theta} \neq \theta \\ 0 & \text{otherwise} \end{cases}$$

$$R(\theta, \hat{\theta}) = \mathbb{E}[1_{\{\hat{\theta}(x) \neq \theta\}}] = P(\hat{\theta} \neq \theta)$$

5.1 Special Case - Hypothesis Testing:

Hypothesis testing can be viewed as a special case in which the parameter θ takes one of two possible values, 0 or 1, and the loss is 0/1 loss or some weighted version of it.

6 Basic Concepts:

- Estimator:

$$\begin{aligned} \hat{\theta} : \mathcal{X} &\rightarrow \Theta \text{ a function of } x \\ \Rightarrow \hat{\theta}(x) &\text{ is a statistic} \end{aligned}$$

- Estimate:

Given a particular observation of X , say x , $\hat{\theta}(x)$ is called the estimate of θ given observation x .

- Bias:

$$\text{bias}(\hat{\theta}) = \mathbb{E}[\hat{\theta}(x)] - \theta$$

- Variance:

$$\begin{aligned}\text{var}(\hat{\theta}) &= \text{tr}(\mathbb{E}[(\hat{\theta}(x) - \mathbb{E}[\hat{\theta}(x)])(\hat{\theta}(x) - \mathbb{E}[\hat{\theta}(x)])^T]) \\ &= \mathbb{E}[(\hat{\theta}(x) - \mathbb{E}[\hat{\theta}(x)])^T(\hat{\theta}(x) - \mathbb{E}[\hat{\theta}(x)])]\end{aligned}$$

- Mean Squared Error (MSE):

$$\begin{aligned}\text{MSE}(\hat{\theta}) &= \mathbb{E}[\|\theta - \hat{\theta}(x)\|_2^2] \\ &= \mathbb{E}[\|\theta - \mathbb{E}[\hat{\theta}(x)] + \mathbb{E}[\hat{\theta}(x)] - \hat{\theta}(x)\|_2^2] \\ &= \|\theta - \mathbb{E}[\hat{\theta}(x)]\|_2^2 + \mathbb{E}[\|\hat{\theta}(x) - \mathbb{E}[\hat{\theta}(x)]\|_2^2] + 2(\theta - \mathbb{E}[\hat{\theta}(x)])^T \underbrace{\mathbb{E}[\hat{\theta}(x) - \mathbb{E}[\hat{\theta}(x)]]}_{=0} \\ &= \underbrace{\text{bias}(\hat{\theta})^T \text{bias}(\hat{\theta})}_{\text{squared bias}} + \underbrace{\text{var}(\hat{\theta})}_{\text{variance}}\end{aligned}$$

- Asymptotics

Suppose $X_1, X_2, \dots, X_n \stackrel{iid}{\sim} p(x|\theta), \theta \in \Theta$, and consider an estimator $\hat{\theta}_n = \hat{\theta}(X_1, \dots, X_n)$. How does $\hat{\theta}_n$ behave as $n \rightarrow \infty$

Definition 1 $\hat{\theta}_n$ is asymptotically unbiased if $\lim_{n \rightarrow \infty} \mathbb{E}[\hat{\theta}_n] - \theta = 0$, for all $\theta \in \Theta$

Definition 2 $\hat{\theta}_n$ is consistent (w.r.t. chosen loss/risk) if $R(\theta, \hat{\theta}_n) \rightarrow 0$, as $n \rightarrow \infty$, for all $\theta \in \Theta$

6.1 A Simple Example

$$\begin{aligned}X_1, X_2, \dots, X_n &\stackrel{iid}{\sim} N(\mu, 1) \\ \hat{\mu}_n &= \hat{\mu}(X_1, \dots, X_n) = \frac{1}{n} \sum_{i=1}^n X_i\end{aligned}$$

- loss: (ℓ_2)

$$\ell(\mu, \hat{\mu}) = \|\mu - \hat{\mu}\|_2^2$$

- risk: (MSE)

$$\begin{aligned}R(\mu, \hat{\mu}) &= \mathbb{E}[\|\mu - \hat{\mu}_n\|_2^2] \\ &= \underbrace{\mathbb{E}[\|\mu - \mathbb{E}[\hat{\mu}_n]\|_2^2]}_{\text{bias}^2} + \underbrace{\mathbb{E}[\|\hat{\mu}_n - \mathbb{E}[\hat{\mu}_n]\|_2^2]}_{\text{variance}}\end{aligned}$$

- bias:

$$\mathbb{E}[\hat{\mu}_n] = \frac{1}{n} \sum_{i=1}^n \mathbb{E}[X_i] = \mu \text{ (unbiased estimator)}$$

- *variance:*

$$\begin{aligned}\mathbb{E}[\|\widehat{\mu}_n - \mathbb{E}[\widehat{\mu}_n]\|_2^2] &= \mathbb{E}[(n \sum_i X_i - \mu)^2] \\ &= \mathbb{E}[\frac{1}{n^2} \left(\sum_i (X_i - \mu) \right)^2] \\ &= \mathbb{E}[\frac{1}{n^2} \sum_{ij} (X_i - \mu)(X_j - \mu)] \\ &= \frac{1}{n^2} \sum_i \mathbb{E}[(X_i - \mu)^2] \\ &= \frac{1}{n}\end{aligned}$$

- *consistency*

$$R(\mu, \widehat{\mu}) = \frac{1}{n} \rightarrow 0 \text{ as } n \rightarrow \infty$$